

Partial Differential Equations

• A PDE is any equation of the form

$$F(u, u_x, u_y, u_{xx}, u_{xy}, u_{yy}, \dots) = 0$$

↳ linear if F depends linearly on u terms, in which case we write $\mathcal{L}u = f$.

↳ obeys similar principles to linear ODEs, i.e. the general solution can be constructed from particular + complementary.

• The diffusion equation:

↳ for a conserved quantity with concentration Q and flux density F , conservation implies $\frac{\partial Q}{\partial t} + \nabla \cdot F = 0$

↳ but the flux depends on the conc. gradient: $F = -\lambda \nabla Q$ Fick's law

$$\Rightarrow \frac{\partial Q}{\partial t} = \lambda \nabla^2 Q \quad \leftarrow \text{reduces to Laplace's equation in the steady state}$$

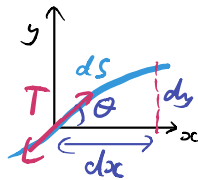
↳ this applies to heat conduction, with $Q = CT$.

• The wave equation:

↳ $m\ddot{y} = F_y \Rightarrow$ pds $\frac{\partial^2 y}{\partial t^2} = \frac{\partial F_y}{\partial x} dx$

↳ $F_y \approx T \frac{\partial y}{\partial x}$ and $\delta s \approx \delta x$

$$\Rightarrow \frac{\partial^2 y}{\partial t^2} = c^2 \frac{\partial^2 y}{\partial x^2}, \quad c = \sqrt{\frac{T}{\rho}}$$



• Types of boundary condition:

↳ Dirichlet: u specified

↳ Neumann: $\frac{\partial u}{\partial x}$ specified

↳ Mixed: some LC of u and $\frac{\partial u}{\partial x}$ specified

• Separation of variables seeks solutions of the form

$$u(x, t) = X(x)T(t)$$

↳ substitute in and rearrange so LHS only contains T, t , RHS only contains X, x .

↳ each side must then equal a constant, so we have 2 ODEs.

↳ for each value of this constant, there may be a different solution. In general, we must sum all.

Laplace's and Poisson's Equations

- Poisson's equation is a 2nd order PDE: $\nabla^2 \psi = \rho(x)$
- For the special case of $\rho=0$, it reduces to Laplace's equation.
- Physical examples:
 - ↳ steady state diffusion
 - ↳ electrostatics: $\nabla^2 \phi = -\rho/\epsilon_0$
 - ↳ gravitation: $\nabla^2 \phi = 4\pi G \rho$
 - ↳ ideal irrotational fluid flow
- The general solution to Laplace's equation can be written as a LC of a set of basis solutions.

Polar coordinates

- Laplace's equation: $\frac{1}{r} \frac{\partial}{\partial r} (r \frac{\partial \psi}{\partial r}) + \frac{1}{r^2} \frac{\partial^2 \psi}{\partial \phi^2} = 0$
- For separable solutions: $\frac{r}{R} \frac{d}{dr} (r R') = -\frac{1}{\Phi} \Phi'' = \lambda$
- If ψ is a physical quantity, it must be 2π -periodic in ϕ . Else if it is a potential, ψ' must be periodic.
 - ↳ so $\lambda = n^2$, and we have cases $n=0$, $n \neq 0$.

$$\Phi(\phi) = \begin{cases} A + B\phi & n=0 \\ A \cos n\phi + B \sin n\phi & n \neq 0 \end{cases}$$

$$\Rightarrow R(r) = \begin{cases} C \ln r + D, & n=0 \\ Cr^n + Dr^{-n}, & n \neq 0 \end{cases}$$

↳ R can be solved using $r=e^+$ sub.

- The general solution is then:

$$\psi(r, \phi) = (A_0 + B_0 \phi) (C_0 \ln r + D_0) + \sum_{n=1}^{\infty} (A_n r^n + B_n r^{-n}) \cos n\phi + \sum_{n=1}^{\infty} (B_n r^n + D_n r^{-n}) \sin n\phi$$

normally disappears due to periodicity.

Spherical coordinates (axisymmetric)

- Axisymmetry implies independence of ϕ (i.e. surface of revolution around z-axis)
- Laplace's equation: $\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \frac{\partial \psi}{\partial r}) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \frac{\partial \psi}{\partial \theta}) = 0$
- Separate: $\frac{1}{R} \frac{d}{dr} (r^2 R') = -\frac{1}{\Theta \sin \theta} \frac{d}{d\theta} (\sin \theta \Theta') = \lambda$
- With the substitution $u = \cos \theta$, $\frac{d}{d\theta} = -\sin \theta \frac{d}{du}$
 - $\Rightarrow \frac{d}{du} ((1-u^2) \frac{d\Theta}{du}) + \lambda \Theta = 0$
 - ↳ i.e. the angular part satisfies Legendre's equation.
 - ↳ $\lambda = l(l+1)$, $l=0,1,2$ and $\Theta_l = P_l(\cos \theta)$
- The general solution is then:

$$\psi(r, \theta) = \sum_{l=0}^{\infty} (A_l r^l + \frac{B_l}{r^{l+1}}) P_l(\cos \theta)$$

- Fitting B.C.s may require integrating over the Legendre polynomials exploiting orthogonality: $\int_{-1}^1 P_m(x) P_n(x) dx = \frac{2}{2m+1} \delta_{mn}$.

Uniqueness

- Suppose there are two solutions Φ_1, Φ_2 . Consider the difference of these solutions $\Psi = \Phi_1 - \Phi_2$
- $\nabla \cdot (\Psi \nabla \Psi) = (\nabla \Psi) \cdot (\nabla \Psi) + \Psi \nabla^2 \Psi$ { zero because Poisson's equation is linear }
- $= |\nabla \Psi|^2$
- ↳ applying the divergence theorem, $\int_V |\nabla \Psi|^2 dV = \oint_S (\Psi \nabla \Psi) \cdot d\mathbf{s}$
- ↳ given Dirichlet boundary conditions, i.e. $\Phi = f(\underline{r})$ on S , $\Psi = 0$ when evaluated on $S \Rightarrow \int_V |\nabla \Psi|^2 dV = 0$
- ↳ $\Psi = 0$ on S and $\nabla \Psi = 0$ inside $\Rightarrow \Psi = 0$
- ↳ hence $\Phi_1 = \Phi_2$ so any solution is unique.
- For Neumann boundary conditions, $\hat{n} \cdot \nabla \Phi = 0$ on S ; the proof is similar.

The Fundamental solution

- Consider Poisson's equation with Dirichlet conditions on a surface S which bounds a volume V .
- The Green's function for this problem is given by:

$$\nabla^2 G(\underline{r}, \underline{r}') = \delta^{(3)}(\underline{r} - \underline{r}'), \quad \underline{r} \in V$$

$$G(\underline{r}, \underline{r}') = 0, \quad \underline{r} \notin V$$

$$\hookrightarrow \delta^{(3)}(\underline{r} - \underline{r}') \equiv \delta(x-x')\delta(y-y')\delta(z-z')$$

$$\hookrightarrow \int_V f(\underline{r}') \delta^{(3)}(\underline{r} - \underline{r}') dV = \begin{cases} f(\underline{r}') & \underline{r}' \in V \\ 0 & \underline{r}' \notin V \end{cases}$$

- ↳ the Green's function is symmetric, i.e. $G(\underline{r}, \underline{r}') = G(\underline{r}', \underline{r})$
- ↳ if V is all space, G is called the **fundamental solution**.
- The Green's function is the potential due to a point charge at \underline{r}' , hence the symmetry is obvious.
- For Neumann B.C.s, G needs a different form on S

$$\frac{\partial G}{\partial n} = \frac{1}{A}, \quad A \equiv \oint_S d\mathbf{s} \quad \leftarrow \text{before we had } G=0 \text{ on } S$$

$$\hookrightarrow \text{this arises because } \int_S \frac{\partial G}{\partial n} d\mathbf{s} = \int_S \nabla G \cdot \hat{n} d\mathbf{s} = \int_V \nabla^2 G dV, \text{ but } \int_V \nabla^2 G dV = \int_V \delta^{(3)}(\underline{r} - \underline{r}') dV = 1.$$

- Consider a point charge at the origin of 3D space. The fundamental solution is given by $\nabla^2 G = \delta^{(3)}(\underline{r})$ with $G \rightarrow 0$ as $|\underline{r}| \rightarrow \infty$.
- By symmetry, G is radial: $\frac{\partial}{\partial r} (r^2 \frac{\partial G}{\partial r}) = 0$ ← for $r \neq 0$
- $\Rightarrow G(r) = A + \frac{C}{r}$
- ↳ $A = 0$ to satisfy B.C. at ∞ .
- ↳ C can be found by integrating $\nabla^2 G$ over a small sphere

$$\int_{r \leq \epsilon} \nabla^2 G dV = \oint_{r=\epsilon} \frac{\partial G}{\partial r} d\mathbf{s} = -\frac{C}{\epsilon^2} \oint_{r=\epsilon} d\mathbf{s} = -4\pi C$$

$$\underbrace{\hspace{10em}}_{=1} \Rightarrow C = -\frac{1}{4\pi}$$

- Hence if we shift the origin to \underline{r}' : $G(\underline{r}, \underline{r}') = -\frac{1}{4\pi|\underline{r} - \underline{r}'|}$

• For a line of charge, the problem is equivalent to finding a 2D Green's function, $\nabla^2 G = \delta^{(2)}(\underline{r})$

$$\Rightarrow G(r) = A + C \ln r$$

↳ we can no longer force $G \rightarrow 0$ as $r \rightarrow \infty$

↳ to find C , we use the 2D divergence theorem for a small circle of radius ϵ .

$$\int_{r \leq \epsilon} \nabla^2 G dA = 2\pi C \Rightarrow C = 1/2\pi$$

↳ hence G is only defined to within an additive constant:

$$G = \frac{1}{2\pi} \ln |\underline{r} - \underline{r}'| + \text{const.}$$

The method of images

• The method of images can be used to find G in some other simple geometries (the fundamental solution only applies in all-space).

• 3D half-space, i.e. $z > 0$:

↳ need G to satisfy $\nabla^2 G = \delta^{(3)}(\underline{r} - \underline{r}')$, $\underline{r} \in D$

$$G \rightarrow 0 \text{ as } |\underline{r}| \rightarrow \infty$$

$$G = 0 \text{ at } z = 0 \leftarrow \text{new B.C. (Dirichlet)}$$

↳ we can construct a solution in \mathbb{R}^3 that fits this by placing an image charge at $\underline{r}'' = (x', y', -z')$, with opposite sign $\therefore \nabla^2 G = \delta^{(3)}(\underline{r} - \underline{r}') + \delta^{(3)}(\underline{r} - \underline{r}'')$

$$\Rightarrow G(\underline{r}, \underline{r}') = -\frac{1}{4\pi|\underline{r} - \underline{r}'|} + \frac{1}{4\pi|\underline{r} - \underline{r}''|}$$

↳ by uniqueness, this is the solution

↳ if we instead had Neumann bounds, i.e. $\frac{\partial G}{\partial z}|_{z=0} = 0$, we could use an image charge with the same sign.

• The image for a charge in a sphere ^{radius a} has strength $-\frac{a}{r'}$ and is located at r'' : $\frac{r''}{a} = \frac{a}{r'}$. It can be shown that this gives $G = 0$ when $r = a$ as needed.

• For a circle, the image has strength -1 and is located again at the inverse point $\frac{r''}{a} = \frac{a}{r'}$.

The integral solution of Poisson's equations

• For smooth functions ϕ, ψ in volume V enclosed by S , Green's identity states

$$\int_V (\phi \nabla^2 \psi - \psi \nabla^2 \phi) dV = \oint_S (\phi \frac{\partial \psi}{\partial n} - \psi \frac{\partial \phi}{\partial n}) dS$$

↳ follows directly from the divergence theorem

↳ can be used in 2D, for surface S enclosed by curve C

• This can be used to find the integral solution once we know the Green's function, letting $\psi \equiv G$ and solving $\nabla^2 \phi = \rho(\underline{r})$.

• For Dirichlet B.Cs, $\phi = f$ on S

↳ Green's identity gives

$$\int_V (\phi \delta^{(3)}(\underline{r} - \underline{r}') - \rho) dV = \oint_S f \nabla G \cdot \hat{n} dS$$

$$\Rightarrow \boxed{\phi(r') = \int_V \rho(r) G(r, r') dV + \oint_S f(r) \frac{\partial G}{\partial n} dS}$$

↳ if V is all space and $f \rightarrow 0$ as $|r| \rightarrow \infty$, then provided

G and ϕ decrease fast enough ($\propto \frac{1}{r}$):

$$\phi(r') = \int_{\mathbb{R}^3} \rho(r) G(r, r') dV$$

• For Neumann B.C.s, $\frac{\partial G}{\partial n} = \frac{1}{A}$, $\frac{\partial \phi}{\partial n} = g(r)$ on S : *arbitrary*

$$\phi(r') = \int_V \rho(r) G(r, r') dV - \oint_S g(r) G(r, r') dS + C$$