

Fluid Equations

- A **fluid element** must be:
 - ↳ small enough so that macroscopic properties \sim const
 - ↳ large enough to have a large number of particles.
- **Collisional fluids** have a small mean-free-path λ :
 - ↳ particles maximise entropy
 - ↳ well-defined pressure $p = p(\rho, T)$ ← equation of state
- **Collisionless fluids** have non-local effects and depend on I.C.s.
- Two frameworks for describing fluids:
 - ↳ **Eulerian** → consider fluid properties as time-varying fields, e.g. $\rho(\underline{r}, t)$, $p(\underline{r}, t)$, $T(\underline{r}, t)$, $\underline{v}(\underline{r}, t)$
 - ↳ **Lagrangian** → perspective of a particular fluid element as time progresses (co-moving frame)
- Consider how quantity $Q(\underline{r}, t)$ changes in the Lagrangian picture

$$\frac{DQ}{Dt} = \lim_{\delta t \rightarrow 0} \left[\frac{Q(\underline{r} + \delta \underline{r}, t + \delta t) - Q(\underline{r}, t)}{\delta t} \right]$$

$$\Rightarrow \boxed{\frac{DQ}{Dt} = \frac{\partial Q}{\partial t} + \underline{u} \cdot \nabla Q} \leftarrow \text{Lagrangian} \leftrightarrow \text{Eulerian}$$

↳ convective derivative: gradient projected onto flow

- 3 ways to describe particle trajectories:
 - ↳ **streamlines** show the velocity field at a given time, i.e. shows instantaneous tangents
 - ↳ **pathlines** show the paths taken by individual fluid elements
 - ↳ **streaklines** connect all points that passed through a particular reference point (e.g. after releasing a drop of dye).
 - ↳ all 3 coincide if $\frac{\partial \underline{u}}{\partial t} = 0 \Rightarrow$ **steady flow**

Conserved quantities

- **Conservation of mass:**

$$\hookrightarrow \frac{dm}{dt} = - \text{rate of outflow}$$

$$\frac{\partial}{\partial t} \int_V \rho dV = - \int_S \rho \underline{u} \cdot d\underline{s}$$

↳ div. theorem

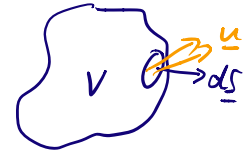
$$\Rightarrow \int_V \left(\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \underline{u}) \right) dV = 0$$

$$\Rightarrow \boxed{\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \underline{u}) = 0} \rightarrow \text{continuity equation (Eulerian)}$$

$$\hookrightarrow \text{easy to derive Lagrangian form: } \frac{D\rho}{Dt} = \frac{\partial \rho}{\partial t} + \underline{u} \cdot \nabla \rho$$

$$\Rightarrow \boxed{\frac{D\rho}{Dt} + \rho \nabla \cdot \underline{u} = 0}$$

- For an **incompressible flow**, $\frac{D\rho}{Dt} = 0 \Rightarrow \nabla \cdot \underline{u} = 0$, i.e. the fluid is divergence-free.



The forces in a fluid are described with the stress tensor σ_{ij}

$\hookrightarrow dF_i = \sigma_{ij} dS_j$

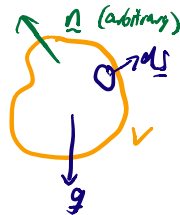
\hookrightarrow for an isotropic fluid, $\sigma_{ij} = p\delta_{ij} \Rightarrow dF = p dS$

Derive cons momentum by considering a fluid element subject to gravity and internal pressure

\hookrightarrow consider all quantities projected onto \hat{n}

\hookrightarrow pressure force = $-\int_S p \hat{n} \cdot dS = -\int_V \hat{n} \cdot \nabla p dV$

\hookrightarrow NII: $\left(\frac{D}{Dt} \int_V p \underline{u} dV\right) \cdot \hat{n} = -\int_V \hat{n} \cdot \nabla p dV + \int_V p \underline{g} \cdot \hat{n} dV$



\hookrightarrow fluid element so $\int dV \rightarrow \delta V$

$$\rho \frac{D\underline{u}}{Dt} = -\nabla p + \rho \underline{g}$$

$$\rho \frac{\partial u}{\partial t} + \rho (\underline{u} \cdot \nabla) u = -\nabla p + \rho \underline{g}$$

\rightarrow momentum equations

\rightarrow easier to derive with box



Consider the Eulerian rate of chg of momentum density

$\partial_t(\rho u_i) = \rho \partial_t u_i + u_i \partial_t \rho$ \rightarrow sub cont & mom. equations

$= -\rho u_j \partial_j u_i - \partial_j p \delta_{ij} + \rho g_i - u_i \partial_j (\rho u_j)$

$= -\partial_j (\underbrace{\rho u_i u_j + p \delta_{ij}}_{\equiv \sigma_{ij}}) + \rho g_i$

\hookrightarrow rewrite as $\partial_t(\rho u) = -\nabla \cdot (\underbrace{\rho \underline{u} \otimes \underline{u} + p \underline{I}}_{\text{Flux of momentum density}}) + \rho \underline{g}$

$\hookrightarrow \rho u_i u_j$ is a 'ram' pressure due to momentum flux of the bulk flow

Gravitation

$\bullet g(\underline{r}) = -G \int_V \rho(\underline{r}') \frac{\underline{r}-\underline{r}'}{|\underline{r}-\underline{r}'|^3} dV'$

\bullet Gives Poisson's equation: $\begin{cases} \nabla \cdot \underline{g} = -\nabla^2 \Psi = -4\pi G \rho \\ \int_S \underline{g} \cdot dS = -4\pi G M_{enc} \end{cases}$

\bullet Potential of a spherically-symmetric system:

$g(r) = \frac{GM_{enc}}{r^2} = \frac{d\Psi}{dr}$

$\Rightarrow \Psi = \int_{\infty}^{r_0} \frac{G}{r^2} \left(\int_0^r 4\pi \rho(r') r'^2 dr' \right) dr$

$\Psi(r) = -\frac{GM(r_0)}{r_0} + \int_{\infty}^{r_0} 4\pi G \rho(r') r dr$

\bullet The GPE of a system is $\Omega = \frac{1}{2} \int \rho(\underline{r}) \Psi(\underline{r}) dV$

\bullet Consider the moment of inertia of a composite system \leftarrow arbitrary origin

$I = \sum_i m_i r_i^2 \Rightarrow \frac{1}{2} \frac{d^2 I}{dt^2} = \sum_i (\underline{r}_i \cdot \underline{F}_i + m_i \dot{r}_i^2)$

$\hookrightarrow \sum_i \underline{r}_i \cdot \underline{F}_i$ is the GPE \leftarrow assume isolated system and forces are either local or gravitational

$\hookrightarrow \sum_i m_i \dot{r}_i^2$ is twice the KE

\hookrightarrow for a system in the steady state, $\frac{d^2 I}{dt^2} = 0$

\hookrightarrow combine to give the Virial theorem: $2T + \Omega = 0$

\bullet The Virial thm relates mass, velocity, size:

$T = \frac{1}{2} M \langle v^2 \rangle, \Omega = -\frac{GM^2}{\bar{r}} \Rightarrow \langle v^2 \rangle = \frac{GM}{\bar{r}}$ \leftarrow mass-weighted avg size.

$\hookrightarrow E_{tot} = T + \Omega = -T = -\frac{1}{2} M \langle v^2 \rangle$, so as 'temp' T (higher $\langle v^2 \rangle$), energy decreases \Rightarrow negative heat capacity

\hookrightarrow this is why structures form from smooth ICs.

Equations of State

- We have 3 scalar + 1 vector unknowns: ρ, u, p, Ψ , but only 3 eqs (continuity, momentum, Poisson).
- The **equation of state** provides the additional constraint.
- For a **barotropic fluid**, pressure is only a function of density: $p = p(\rho)$
 - e.g. electron degeneracy pressure: $p \propto \rho^{5/3}$
 - e.g. isothermal ideal gas: $p \propto \rho$. This occurs when strong heating and strong cooling balance at a well-defined temp.
 - e.g. adiabatic ideal gas $p = k\rho^\gamma$.
- Fluid elements may each be adiabatic ($p = k\rho^\gamma$ with k const), but k may vary between elements \rightarrow **isentropic** if all have same k (because $\ln k \propto \int dm$).

The Energy Equation

- From the 1st law of thermo, $\frac{DE}{Dt} = \frac{dQ}{dt} + \frac{dW}{Dt}$
 - $\rightarrow dW = -pdV \Rightarrow \frac{dW}{Dt} = -\rho \frac{D}{Dt} \left(\frac{1}{\rho} \right) = \frac{p}{\rho^2} \frac{D\rho}{Dt}$ ← for unit mass, $V = \frac{1}{\rho}$
 - $\rightarrow \frac{dQ}{dt} \equiv -\dot{Q}_{cool} \Rightarrow \frac{DE}{Dt} = \frac{p}{\rho^2} \frac{D\rho}{Dt} - \dot{Q}_{cool}$

The total energy of a fluid is $E = \rho \left(\frac{1}{2} u^2 + \Psi + \epsilon \right)$

$$\Rightarrow \frac{DE}{Dt} = \frac{D\rho}{Dt} \frac{E}{\rho} + \rho \left(u \cdot \nabla u + \frac{D\Psi}{Dt} + \frac{p}{\rho^2} \frac{D\rho}{Dt} - \dot{Q}_{cool} \right)$$

\rightarrow write everything in Eulerian, we know equations

$$\frac{\partial E}{\partial t} + \nabla \cdot [(E+p)u] = \rho \frac{\partial \Psi}{\partial t} - \rho \dot{Q}_{cool} \quad \leftarrow \text{Energy equation}$$

- \rightarrow LHS describes change in total energy due to the divergence of the **enthalpy flux** ($(E+p)u$).
- \rightarrow RHS contains sources of energy. If no external sources, $\frac{\partial E}{\partial t} = \text{div}(\text{enthalpy flux})$.

Heating and cooling ← Astrophysical examples

- Most cooling processes involve radiation.
 - Collisionally excited atomic line radiation**: ← electron-ion collision
 - \rightarrow collision excites atom, which later emits a photon with energy χ
 - \rightarrow luminosity per unit volume: $L_c \propto n_e n_{ion} e^{-\chi/kT} \chi / T$
 - num. collisions energy per collision
 - \rightarrow divide by ρ to get \dot{Q} (which is per unit mass)
 - Recombination emission**:
 - \rightarrow free electron captured in high energy state
 - \rightarrow cascades down, releasing photons in the process.
 - \rightarrow as above, $\dot{Q} \propto \rho f(T)$
 - Free-free emission** (bremsstrahlung): electrons accelerated by nuclei so radiate. $\dot{Q} = A_0 \rho \sqrt{T}$

- Heating can occur internally, e.g. shocks or viscous flows.
- Cosmic rays are an external source of heat, with $\dot{Q} \propto \text{ray flux}$
- Combine heating and cooling to get $\dot{Q}_{cool} = A\rho T^\alpha - H_c$ ← CR cooling

Energy transport

- Thermal conduction: transfer of thermal energy down temp. ^{diffusion process} gradients
 - ↳ energy flux: $F_{\text{cond}} = -K \nabla T$
 - ↳ so the rate of change of energy density is $-\nabla \cdot F_{\text{cond}} = \kappa \nabla^2 T$
 - ↳ important in white dwarfs, supernova shocks
- Radiation transport:
 - ↳ in optically thick systems, radiation transports energy rather than cooling
 - ↳ radiative diffusion: $F_{\text{rad}} \propto -\nabla \epsilon_{\text{rad}}$
- Convection \rightarrow circulating fluid motion (important in stars)

Stellar Fluids

- In static equilibrium, $u=0$, $\frac{\partial}{\partial t}=0$
 - ↳ momentum equation $\Rightarrow \nabla p = -\rho \nabla \Psi \leftarrow \text{HSE}$
 - ↳ i.e. pressure forces must balance gravity
- For a self-gravitating system, HSE must be solved together with Poisson's equation.
- Example: isothermal atmosphere with constant external g
 - ↳ $g = -g \hat{z}$, $p = \frac{RT}{M} \rho = A \rho$
 - $\Rightarrow A \nabla p = -\rho g \hat{z} \Rightarrow A \frac{dp}{\rho} = -g$
 - ↳ $\ln \rho = -\frac{gz}{A} + \text{const} \Rightarrow \rho = \rho_0 e^{-\frac{g}{A} z}$
 - ↳ good model for Earth atmosphere
- Example: isothermal self-gravitating slab
 - ↳ $A \nabla p = -\rho \nabla \Psi \Rightarrow A \frac{dp}{dz} = -\rho \frac{d\Psi}{dz} \Rightarrow \Psi = -A \ln(\rho/\rho_0) + \Psi_0$
 - $\Rightarrow \rho = \rho_0 e^{-(\Psi - \Psi_0)/A}$
 - ↳ to proceed, use Poisson: $\frac{d^2 \Psi}{dz^2} = 4\pi G \rho_0 e^{-(\Psi - \Psi_0)/A}$
 - ↳ can model galaxy
- Model a star as a spherically-symmetric self-gravitating system in HSE.
 - ↳ HSE in spherical polar: $\frac{dp}{dr} = -\rho \frac{d\Psi}{dr}$
 - ↳ $\rho > 0$ so ρ is a monotonically decreasing function of Ψ
 - ↳ $\frac{dp}{dr} = \frac{dp}{d\Psi} \frac{d\Psi}{dr} = -\rho \frac{d\Psi}{dr} \Rightarrow \rho = -\frac{dp}{d\Psi} \leftarrow$ also monotonic

- ↳ $p = p(\Psi)$, $\rho = \rho(\Psi) \Rightarrow p = p(\rho) \Rightarrow$ stars are barotropic
- A useful family of barotropes is $p = K\rho^{1+1/n}$, where $n = n(\rho)$
 - ↳ polytropes have $n = \text{const}$
 - ↳ if the star is isentropic (e.g. fully convective), $1 + \frac{1}{n} = \gamma \equiv \frac{C_p}{C_v}$, so the polytrope equation is the adiabatic eq. of state.
 - Solve HSE + Poisson to get structure of polytrope:
 - ↳ $-\nabla^2 \Psi = \frac{1}{\rho} \nabla \cdot (K\rho^{1+1/n}) = (n+1) \nabla \cdot (K\rho^{1/n})$
 - $\Rightarrow \rho = \left(\frac{\Psi_T - \Psi}{(n+1)K} \right)^n$, where $\Psi_T \equiv \Psi$ when $\rho = 0$ (tidal potential)
 - ↳ the central density: $\rho_c = \left(\frac{\Psi_T - \Psi_c}{(n+1)K} \right)^n \Rightarrow \rho = \rho_c \left(\frac{\Psi_T - \Psi}{\Psi_T - \Psi_c} \right)^n$
 - ↳ let $\theta \equiv \frac{\Psi_T - \Psi}{\Psi_T - \Psi_c}$ and use a dimensionless radial coordinate ξ
 - ↳ gives the Lane-Emden equation: $\frac{1}{\xi^2} \frac{d}{d\xi} \left(\xi^2 \frac{d\theta}{d\xi} \right) = -\theta^n$
 - ↳ at $\xi = 0$ (centre), $\theta = 1$ and $\frac{d\theta}{d\xi} = 0$
 - Lane-Emden can be solved for $n=0, n=1, n=5$.
 - The limit $n \rightarrow \infty$ gives the isothermal sphere: $\frac{1}{\xi^2} \frac{d}{d\xi} \left(\xi^2 \frac{d\theta}{d\xi} \right) = e^{-\theta}$
 - ↳ $\rho \propto r^{-2}$ as $r \rightarrow \infty$, so mass does not converge.
 - ↳ in practice, we truncate at a finite radius \rightarrow Bonnor-Ebert spheres

Scaling relations \rightarrow C.F. Stellar Homology

- Consider families of stars with the same polytrope index. The shape of the density curve in each star will be the same
- Using the rescaled coordinates:
 - $\rho = \left(\frac{\Psi_T - \Psi}{(n+1)K} \right)^n \Rightarrow \Psi_T - \Psi_c = K(n+1)\rho_c^{1/n}$
 - $\therefore \xi = r \sqrt{\frac{4\pi G \rho_c}{\Psi_T - \Psi_c}} = r \sqrt{\frac{4\pi G \rho_c^{1-1/n}}{K(n+1)}}$, $\rho = \rho_c \theta^n$
 - ↳ at the surface, $\xi = \xi_{\text{max}}$, $\theta(\xi_{\text{max}}) = 0$
- The mass of a polytrope is:
 - $M = \int_0^{r_{\text{max}}} 4\pi r^2 \rho dr = 4\pi \rho_c \left[\frac{4\pi G \rho_c^{1-1/n}}{K(n+1)} \right]^{-3/2} \int_0^{\xi_{\text{max}}} \theta^n \xi^2 d\xi$ ↗ Same for a given n
 - $\Rightarrow M \propto \rho_c^{1/2} \left(\frac{3}{n} - 1 \right)$
 - ↳ radius relation comes from def. of ξ : $r_{\text{max}} \propto \rho_c^{1/2} \left(\frac{3}{n} - 1 \right)$
 - ↳ eliminate ρ_c to get the mass-radius relation: $M \propto R^{3-n/(1-n)}$
- For white dwarfs, $\gamma = 5/3 \Rightarrow n = 3/2$, so $R \propto M^{-1/3}$. More massive WDs are smaller.
- However, $R \propto M^{-1/3}$ is wrong for most stars, because it assumes K is constant:
 - $\left. \begin{aligned} p &= K\rho^{1+1/n} \\ p &= \frac{R_*}{M_*} \rho T \end{aligned} \right\} \Rightarrow T_c = \frac{M_*}{R_*} \rho_c^{1/n}$
 - ↳ T_c is similar in all stars (nuclear reactions) $\Rightarrow K \propto \rho_c^{-1/n}$
 - $\Rightarrow M \propto \rho_c^{-1/2}$, $R \propto \rho_c^{-1/2} \Rightarrow M \propto R$ as observed
 - ↳ we can use $K = \text{const}$ on an individual star when mass is changing on a fast timescale (before thermal eq. is established).

Sound Waves

Equilibrium fluid

$$\begin{aligned} \rho &= \rho_0 \\ p &= p_0 \\ u &= 0 \end{aligned} \left. \begin{array}{l} \text{uniform} \\ \text{constant} \end{array} \right\}$$

Small perturbation (Lagrangian)

$$\begin{aligned} \rho &= \rho_0 + \Delta\rho \\ p &= p_0 + \Delta p \\ u &= \Delta u \end{aligned}$$

• Eulerian perturbation: $\delta Q = \Delta Q - (\xi \cdot \nabla) Q$ ← element of displacement

↳ same as Lagrangian for uniform medium

• Apply perturbation to continuity/momentum eq. (to 1st order)

↳ continuity $\Rightarrow \frac{\partial}{\partial t} \Delta\rho + \rho_0 \nabla \cdot (\Delta u) = 0$

↳ momentum $\Rightarrow \frac{\partial}{\partial t} (\Delta u) = -\frac{1}{\rho_0} \nabla (\Delta p)$
 $= -\frac{d\rho}{d\rho} \Big|_{\rho_0} \frac{\nabla(\Delta p)}{\rho_0}$ ← barotropic Eq of state

↳ combine linearised eqs: $\frac{\partial^2(\Delta p)}{\partial t^2} = \frac{d\rho}{d\rho} \Big|_{\rho_0} \cdot \nabla^2(\Delta p)$ ← wave eq.

• Guess plane wave solution $\Delta p = \Delta p_0 e^{i(k \cdot x - \omega t)}$

↳ $\omega^2 = \frac{d\rho}{d\rho} \Big|_{\rho_0} k^2 \Rightarrow$ dispersionless waves

↳ speed of sound: $c_s = \sqrt{\frac{d\rho}{d\rho} \Big|_{\rho_0}}$

• Can relate density \leftrightarrow velocity perturbations:

↳ sub. $\Delta u, \Delta p$ into continuity eq $\Rightarrow -i\omega \Delta\rho + \rho_0 i k \Delta u = 0$
 $\Rightarrow \Delta u = \frac{\omega}{k} \frac{\Delta\rho}{\rho_0} = c_s \frac{\Delta\rho}{\rho_0}$

↳ velocity and density perturb. in phase

↳ $\Delta u \ll c_s$, i.e. sound wave much faster than fluid.

Sound waves in a stratified atmosphere

• E.g. propagation through an isothermal atmosphere in HSE:

↳ $u_0 = 0$, $\rho_0(z) = \tilde{\rho} e^{-z/H}$, $p_0(z) = \tilde{p} e^{-z/H}$, $H = \frac{R^* T}{gM}$

↳ sound waves in the z direction are different

• With $g = -g \hat{z}$, momentum eq. becomes $\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial z} - g$

↳ substitute Eulerian perturbations then convert to Lagrangian

↳ continuity $\Rightarrow \frac{\partial \Delta\rho}{\partial t} + \rho_0 \frac{\partial \Delta u_z}{\partial z} = 0$ (same as before)

↳ momentum $\Rightarrow \frac{\partial \Delta u_z}{\partial t} = -\frac{c_u^2}{\rho_0} \frac{\partial \Delta p}{\partial z}$, $c_u \equiv \frac{\partial p}{\partial \rho} \Big|_{\rho_0}$

↳ combine to give: $\frac{\partial^2 \Delta\rho}{\partial t^2} - c_u^2 \frac{\partial^2 \Delta\rho}{\partial z^2} + \frac{c_u^2}{\rho_0} \frac{\partial \rho_0}{\partial z} \frac{\partial \Delta\rho}{\partial z} = 0$
 wave eq $= -\frac{\rho_0}{H}$

• Guessing plane wave solution: $\omega^2 = c_u^2 (k^2 - \frac{ik}{H})$ ← dispersion relation

$$k = \frac{i}{2H} \pm \sqrt{\frac{\omega^2}{c_u^2} - \frac{1}{4H^2}}$$

Case 1: $\omega > c_u/2H$

↳ $\Delta p \propto e^{-z/2H} e^{i(\text{Re}(k) - \omega t)}$

↳ $\frac{\Delta p}{\rho_0} \propto e^{z/2H}$, so perturbation theory fails eventually



Case 2: $\omega < c_u/2H$

↳ $\Delta p \propto e^{-kz} e^{i\omega t}$ ← evanescent wave

Shocks

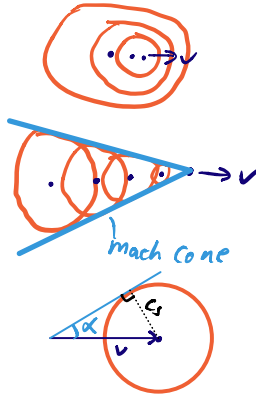
In an isotropic medium, sound wavefronts are circular

↳ for a moving source, the centres of subsequent wavefronts are displaced

↳ if $v > c_s$, a Mach cone forms:

↳ the cone separates disturbed & undisturbed with a shockwave

↳ the Mach number is $M \equiv \frac{v}{c_s}$; it determines the shape of the cone: $\sin \alpha = \frac{c_s}{v} = \frac{1}{M}$



For supersonic flows, the fluid may travel faster than signals can be transmitted \rightarrow leads to discontinuities when the bulk 'realises' it has collided with something \rightarrow shocks.

Work in the reference frame of the shock.

Integrate fluid equations over a small volume dx to get the Rankine-Hugoniot relations

Continuity: $\frac{\partial}{\partial t} (\int_{\sigma} \rho dx) = \rho u|_0 + \rho u|_0 -$

↳ in steady state, mass does not accumulate at $x=0 \Rightarrow \frac{\partial}{\partial t} [\cdot] = 0$

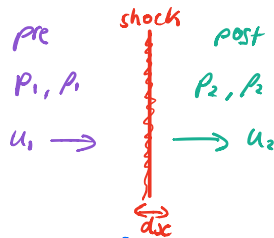
$\Rightarrow \rho_1 u_1 = \rho_2 u_2 \leftarrow 1^{st} \text{ R-H relation}$

Momentum: $\rho_1 u_1^2 + p_1 = \rho_2 u_2^2 + p_2 \leftarrow 2^{nd} \text{ R-H}$

Energy equation for an adiabatic shock:

$\frac{\partial E}{\partial t} + \nabla \cdot [(E+p)u] = 0 \Rightarrow (E_1 + p_1)u_1 = (E_2 + p_2)u_2$

↳ $E = \rho(\frac{1}{2}u^2 + \epsilon + \Psi) \Rightarrow \frac{1}{2}u_1^2 + \epsilon_1 + \frac{p_1}{\rho_1} = \frac{1}{2}u_2^2 + \epsilon_2 + \frac{p_2}{\rho_2} \leftarrow 3^{rd} \text{ R-H}$



↳ can rewrite R-H III in terms of sound speed

$\epsilon = \frac{1}{\gamma-1} \frac{p}{\rho}, c_s^2 = \frac{\partial p}{\partial \rho} \Rightarrow \frac{1}{2}u_1^2 + \frac{c_{s1}^2}{\gamma-1} = \frac{1}{2}u_2^2 + \frac{c_{s2}^2}{\gamma-1}$

Jumps in ρ, p, T can all be written in terms of γ and M

↳ for strong shocks ($M \gg 1$), $\frac{\rho_2}{\rho_1} \rightarrow \frac{\gamma+1}{\gamma-1} = \text{const}$

↳ i.e. there is a maximum density jump for adiabatic shocks.

2nd law of thermo. dictates the direction of the jump

↳ Flow decelerates from super \rightarrow sub-sonic, KE dissipated.

↳ shocks are irreversible due to viscous processes

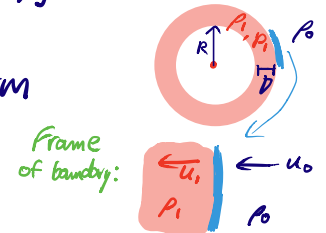
Supernova explosions

Model supernova as point explosion of energy E within an ISM of density ρ_0 , and $p_0=0, T_0=0$.

Creates an expanding layer of shocked ISM

↳ strong shock $\Rightarrow p_1 = \rho_0 \frac{\gamma+1}{\gamma-1}$

↳ shell consists of swept-up mass



$\frac{4}{3} \pi R^3 \rho_0 = 4 \pi R^2 v \rho_1 \Rightarrow v = \frac{1}{3} \frac{\gamma-1}{\gamma+1} R \approx 0.08R$

↳ relative velocity in shell: $U = u_0 - u_1 = u_0 - \frac{\rho_0}{\rho_1} u_0 = \frac{2u_0}{\gamma+1}$

The momentum of the shell is changing as it consumes ISM.

↳ rate of chg of momentum: $\frac{d}{dt} [\frac{4}{3} \pi R^3 \rho_0 \cdot \frac{2u_0}{\gamma+1}]$

↳ caused by pressure inside the cavity. Assume $p_{in} = \alpha p_1$

↳ R-H II gives $p_1 = \frac{2}{\gamma+1} \rho_0 u_0^2 \leftarrow \text{Ram pressure into ISM}$

$$\Rightarrow \frac{d}{dt} \left[\frac{4}{3} \pi R^3 \rho_0 \cdot \frac{2u_0}{\gamma+1} \right] = 4\pi R^2 \dot{p}_1 = 4\pi R^2 \alpha \cdot \frac{2}{\gamma+1} \rho_0 u_0^2$$

$$\Rightarrow \frac{d}{dt} [R^3 u_0] = 3\alpha R^2 u_0^2 \Rightarrow \frac{d}{dt} [R^3 \dot{R}] = 3\alpha R^2 \dot{R}^2 \leftarrow u_0 \equiv \dot{R}$$

↳ seek power law solution $R \propto t^b \Rightarrow b = \frac{1}{4-3\alpha}$

↳ $R \propto t^{1/(4-3\alpha)} \Rightarrow u_0 = \dot{R} \propto R^{3\alpha-3}$

• Determine α by cons energy.

↳ ignore KE of cavity (little mass) and internal energy of shell (thin)

↳ KE of shell: $\frac{1}{2} \frac{4}{3} \pi R^3 \rho_0 u^2$

↳ internal energy of cavity: $\frac{4}{3} \pi R^3 \rho E = \frac{4}{3} \pi R^3 \alpha \frac{p_1}{\gamma-1}$

↳ sum to get $E \propto R^3 u_0^2 \propto t^{(6\alpha-3)/(4-3\alpha)}$

↳ E must be time dependent $\Rightarrow 6\alpha-3=0 \Rightarrow \alpha=1/2$

• Resulting dynamics: $R \propto t^{2/5}, u_0 \propto t^{-3/5}, p_1 \propto t^{-6/5}$

Similarity solutions to supernova explosions

• Previous derivation assumed: uniform shell, $p_{in} \propto p_1$, cold ISM.

• Similarity solutions use dimensional analysis.

• We only specify E and ρ_0

↳ unique combination to get a length scale: $\lambda = \left(\frac{Et^2}{\rho_0} \right)^{1/5}$

↳ define dimensionless distance param $\xi \equiv \frac{r}{\lambda}$

↳ the evolution of any variable in space and time can be

separated into time behaviour \times scale: $X(t,r) = X_1(t) \tilde{X}(\xi)$

• Can rewrite derivatives:

$$\frac{\partial X}{\partial r} = X_1 \frac{d\tilde{X}}{d\xi} \frac{\partial \xi}{\partial r} \Big|_t, \quad \frac{\partial X}{\partial t} = \tilde{X}(\xi) \frac{dX_1}{dt} + X_1 \frac{d\tilde{X}}{d\xi} \frac{\partial \xi}{\partial t} \Big|_r$$

↳ use $\rho(r,t) = X_\rho(t) \tilde{\rho}(\xi)$ etc and sub. into fluid equations

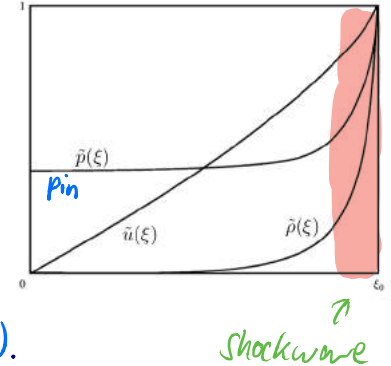
↳ fluid equations become ODEs

• Result is $R_{shock} \propto \left(\frac{E}{\rho_0} \right)^{1/5} t^{2/5}$

↳ most of the mass is indeed swept into a shell

↳ shell pressure is indeed a multiple of p_{in}

↳ can take weighted avg of different shell velocities using the form of $\tilde{u}(\xi)$.



• The SN explosion stalls when $\rho_1 \sim \rho_0$:

$$p_1 = \frac{2}{\gamma+1} \rho_0 u_0^2, \quad c_s^2 = \frac{\gamma p_0}{\rho_0} \Rightarrow \frac{2}{\gamma+1} \rho_0 u_0^2 \sim \frac{\rho_0 c_s^2}{\gamma}$$

$$\Rightarrow u_0 \approx c_s$$

↳ shell no longer supersonic \rightarrow becomes a sound wave

↳ equivalently, when the energy of the explosion = internal energy swept up by the shockwave

Bernoulli's Equation

- Momentum equation: $\frac{\partial \underline{u}}{\partial t} + (\underline{u} \cdot \nabla) \underline{u} = -\frac{1}{\rho} \nabla p - \nabla \Psi$
 - ↳ define the vorticity $\underline{\omega} = \nabla \times \underline{u} \Rightarrow (\underline{u} \cdot \nabla) \underline{u} = \nabla(\frac{1}{2} u^2) - \underline{u} \times \underline{\omega}$
 - ↳ for a barotropic fluid, $p = p(\rho)$

$$\frac{\partial}{\partial x_i} \int \frac{dp}{\rho} = \frac{\partial p}{\partial x_i} \frac{d}{dp} \int \frac{dp}{\rho} = \frac{1}{\rho} \frac{\partial p}{\partial x_i} \Rightarrow -\frac{1}{\rho} \nabla p = \nabla \left(\int \frac{dp}{\rho} \right)$$

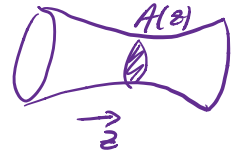
$$\Rightarrow \frac{\partial \underline{u}}{\partial t} + \nabla \left(\frac{1}{2} u^2 \right) - \underline{u} \times \underline{\omega} = -\nabla \left(\int \frac{dp}{\rho} + \Psi \right)$$
 - ↳ for a steady flow, we then have

$$\underline{u} \cdot \nabla \left(\frac{1}{2} u^2 + \int \frac{dp}{\rho} + \Psi \right) = 0$$
- Bernoulli's principle: $H = \frac{1}{2} u^2 + \int \frac{dp}{\rho} + \Psi$ is constant along a streamline (barotropic, steady flow).
- For a general barotropic (unsteady) flow: \leftarrow without viscosity

$$\frac{\partial \underline{u}}{\partial t} = -\nabla H + \underline{u} \times \underline{\omega} \quad \xrightarrow{\nabla \times} \quad \frac{\partial \underline{\omega}}{\partial t} = \nabla \times (\underline{u} \times \underline{\omega}) \quad \leftarrow \text{Helmholtz Equation}$$
 - ↳ the flux of vorticity through a surface S that moves with the fluid is constant: $\frac{D}{Dt} \int_S \underline{\omega} \cdot d\underline{S} = 0$
Kelvin's vorticity theorem
 - ↳ close analogy to magnetic field lines
- If $\underline{\omega} = \underline{0}$, the fluid is irrotational
 - ↳ if irrotational, H is constant everywhere (not just on streamlines)
 - ↳ if $\underline{\omega} = \underline{0}$ it remains so $\Rightarrow \underline{u} = -\nabla \Phi$
 - ↳ if flow is also incompressible, $\nabla \cdot \underline{u} = 0 \Rightarrow \nabla^2 \Phi = 0$

De Laval Nozzle

- Steady state barotropic flow through a nozzle
- Momentum: $\underline{u} \cdot \nabla \underline{u} = -\frac{1}{\rho} \nabla p = -\frac{1}{\rho} c_s^2 \nabla \rho$



- Continuity: $\rho u A = \text{const} \equiv \dot{m}$ $\left. \begin{array}{l} \text{take logs then } \nabla \end{array} \right\}$
 - ↳ $\frac{1}{\rho} \nabla p = -\nabla \ln u - \nabla \ln A$
 - ↳ $\underline{u} \cdot \nabla \underline{u} = [\nabla \ln u + \nabla \ln A] c_s^2$

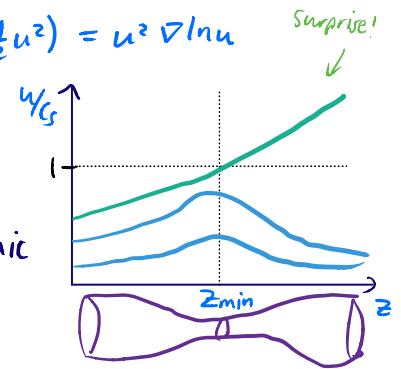
- For irrotational flow, $\underline{u} \cdot \nabla \underline{u} = \nabla(\frac{1}{2} u^2) = u^2 \nabla \ln u$

$$\Rightarrow (u^2 - c_s^2) \nabla \ln u = c_s^2 \nabla \ln A$$

- An extremum in A implies either
 - ↳ extremum in u

- ↳ $u = c_s$, i.e. subsonic \rightarrow supersonic

- ↳ fluid continues to accelerate



- For isothermal EoS, $p = \frac{R^* \rho T}{m} \Rightarrow H = \frac{1}{2} u^2 + c_s^2 \ln \rho$
 - ↳ use Bernoulli equation ($H = \text{const}$) in terms of the min area A_m

$$\Rightarrow u^2 = c_s^2 \left[1 + 2 \ln \left(\frac{uA}{c_s A_m} \right) \right], \text{ using } \rho u A = \text{const}$$
- For a polytropic EoS, c_s varies with density
 - ↳ $p = K \rho^{1+1/n} \Rightarrow c_s^2 = \frac{n+1}{n} K \rho^{1/n}$
 - ↳ $H = \frac{1}{2} \left(\frac{\dot{m}}{A \rho} \right)^2 + n c_s^2$

Spherical accretion

- Consider the spherically symmetric flow of matter onto a point mass. Assume steady state and barotropic EoS
- Continuity: $4\pi r^2 \rho u = \dot{m}$, where u points inwards
 - ↳ in a steady flow, $\frac{d}{dr}(\ln \dot{m}) = 0 \Rightarrow \frac{d}{dr} \ln \rho = -\frac{d}{dr} \ln u - \frac{2}{r}$
- Momentum: $u \frac{du}{dr} = -\frac{1}{\rho} \frac{dp}{dr} - \frac{GM}{r^2} \Rightarrow u^2 \frac{d \ln u}{dr} = -c_s^2 \frac{d \ln \rho}{dr} - \frac{GM}{r^2}$
 - ↳ combine with continuity to get $(u^2 - c_s^2) \frac{d}{dr} \ln u = \frac{2c_s^2}{r} (1 - \frac{GM}{2c_s^2 r})$ (*)
- There is a critical radius $r = r_s = \frac{GM}{2c_s^2} \leftarrow$ sonic point
 - ↳ at $r = r_s$, either $u = c_s$ or u is extremised.
- For isothermal EoS, $c_s = \sqrt{\frac{R_g T}{\mu}} = \text{const}$
 - ↳ $H = \frac{1}{2} u^2 + c_s^2 \ln \rho + \Psi = \text{const}$ (Bernoulli)
 - ↳ compare flow at general point to flow at sonic point
 - $\Rightarrow u^2 = 2c_s^2 \left[\ln\left(\frac{r_s}{r}\right) - \frac{3}{2} \right] + \frac{2GM}{r}$
 - ↳ as $r \rightarrow 0$, $u^2 \rightarrow \frac{2GM}{r}$ (Free fall)
 - ↳ as $r \rightarrow \infty$ and $u \rightarrow 0$, $\rho \rightarrow \rho_s e^{-3/2} \Rightarrow \rho_s = \rho_\infty e^{3/2}$
 - ↳ mass accretion rate: $\dot{m} = 4\pi r_s^2 \rho_s c_s = \frac{\pi G^2 M^2 \rho_\infty e^{3/2}}{c_s^3}$
- For polytropic EoS we repeat the same procedure except substitute $u = \frac{\dot{m}}{4\pi r^2 \rho}$ earlier to simplify
 - $\Rightarrow \dot{m} = \frac{\pi (GM)^2 \rho_\infty}{c_{s0}^3} \left(\frac{n}{n - \frac{3}{2}} \right)^{n-3/2}$ Bondi accretion
 - ↳ in $n \rightarrow \infty$ limit, becomes isothermal
 - ↳ for $n \rightarrow \frac{3}{2}$ ($\gamma = 5/3$), \dot{m} still finite even though c_s, ρ singular.

$$\dot{M} = AM^2 \Rightarrow M = \frac{M_0}{1 - At/M_0}$$

↳ $M \rightarrow \infty$ at finite time

↳ in reality, accretion will be limited by fuel supply or the Eddington limit ($\dot{M} \propto M$)

• Dependence on reservoir properties:

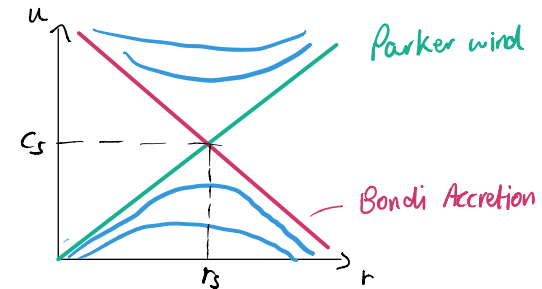
↳ $\dot{m} \propto \frac{\rho_\infty}{c_{s0}^3} \propto \frac{\rho_\infty}{c_{s0}^5} \rightarrow$ higher accretion rates from colder material

↳ for a moving accretion point with velocity v_∞ rel. to medium:

$$\dot{m} \sim \frac{(GM)^2 \rho_\infty}{(c_{s0}^2 + v_\infty^2)^{3/2}} \leftarrow \text{Bondi-Hoyle-Lyttleton}$$

• Another solution to (*) is the Parker wind

↳ physically, the very hot central gas causes an outward wind



• These solutions are very sensitive to assumptions, e.g. nonzero angular momentum / B-fields break symmetry.

Fluid Instabilities

- A fluid is **unstable** if a perturbation to the steady state flow grows with time.
 - ↳ **linearly unstable** if an arbitrarily small perturbation grows
 - ↳ **overstable** if perturbations oscillate with growing amplitude
- **Stable** if perturbation decays/oscillates

Convective instability

- Perturb a fluid element upwards (originally in HSE)
- Pressure will quickly equilibrate (acoustic waves), but there may not be time for heat exchange
 - ↳ density evolves adiabatically.
 - ↳ if $\rho^* < \rho'$, the perturbed element is buoyant and continues to rise \rightarrow unstable.
- Adiabatic density change: $p = k\rho^\gamma \Rightarrow \rho^* = \rho \left(\frac{p^*}{p}\right)^{1/\gamma}$
 - ↳ $p^* = k\rho^{*\gamma}$
 - ↳ $p' = p + \frac{dp}{dz} \delta z \Rightarrow \rho^* = \rho \left(1 + \frac{1}{\gamma} \frac{dp}{p} \frac{dz}{\rho}\right)^{\gamma} \approx \rho + \frac{\rho}{\gamma} \frac{dp}{p} \frac{dz}{\rho}$
 - ↳ density of background atmosphere: $\rho' = \rho + \frac{d\rho}{dz} \delta z$
 - ↳ unstable if $\rho^* < \rho' \Rightarrow \frac{d}{dz} (\ln \rho \rho^\gamma) < 0 \Rightarrow \frac{d\ln \rho}{dz} < 0$
 - ↳ **Schwarzschild criterion**: convective unstable if entropy decreases upwards
 - ↳ temperature: $K \propto \rho^{1-\gamma} T^\gamma \Rightarrow \frac{dT}{dz} < \left(1 - \frac{1}{\gamma}\right) \frac{T}{\rho} \frac{d\rho}{dz}$

- A convectively stable fluid undergoes SHM:

$$\Rightarrow \rho^* \frac{d^2 \delta z}{dt^2} = -g(\rho^* - \rho')$$

$$\Rightarrow \frac{d^2 \delta z}{dt^2} = -\frac{g}{T} \left[\frac{dT}{dz} - \left(1 - \frac{1}{\gamma}\right) \frac{T}{\rho} \frac{d\rho}{dz} \right] \delta z$$

- ↳ **internal gravity waves** oscillating at the Brunt-Väisälä frequency

Gravitational instability

- Equilibrium: $p = p_0 = \text{const}$, $\rho = \rho_0 = \text{const}$, $\Psi = \Psi_0 = \text{const}$, $\underline{u} = 0$
 - ↳ **Jeans swindle**: technically can't have $\rho = \text{const}$ AND $\Psi = \text{const}$
- Governing equations: continuity, momentum, Poisson, barotropic EoS
- Perturb, e.g. $p = p_0 + \Delta p$, $\Psi = \Psi_0 + \Delta \Psi$
- Linearise and assume plane waves: $\Rightarrow \omega^2 = c_s^2 \left(k^2 - \frac{4\pi G \rho_0}{c_s^2} \right)$
 - ↳ define **Jeans wavenumber** $k_J^2 = 4\pi G \rho_0 / c_s^2 \Rightarrow \omega^2 = c_s^2 (k^2 - k_J^2)$
 - ↳ $k \gg k_J \Rightarrow$ normal soundwaves
 - ↳ $k \gtrsim k_J \Rightarrow$ modified sound waves (slower group velocity)
 - ↳ $k < k_J \Rightarrow \omega$ imaginary so perturbations grow exponentially \Rightarrow **gravitational instability**
- Maximum stable wavelength is the **Jeans length** $\lambda_J = \sqrt{\frac{\pi c_s^2}{G \rho_0}}$ with an associated **Jeans mass** $M_J \sim \rho_0 \lambda_J^3$
 - ↳ systems undergo **gravitational collapse** when $M > M_J$
 - ↳ for isothermal collapse, $M_J \propto c_s^3 \rho_0^{-1/2} \propto (T^3 / \rho_0)^{1/2}$ so $M_J \downarrow$ as system collapses \Rightarrow **gravitational fragmentation**.

Interface instabilities

- Interfaces have discontinuous changes in density / tangential velocity
- ↳ assume incompressible and irrotational

$$\nabla \cdot \mathbf{u} = 0, \nabla \times \mathbf{u} = 0 \Rightarrow \mathbf{u} = -\nabla \Phi$$

↳ Φ is a velocity potential satisfying $\nabla^2 \Phi = 0$

↳ split potentials into perturbed and unperturbed

$$\begin{aligned} \Phi_{\text{low}} &= -Ux + \phi \\ \Phi_{\text{up}} &= -U'x + \phi' \end{aligned} \Rightarrow \nabla^2 \phi = \nabla^2 \phi' = 0$$

↳ seek plane wave solutions

$$\begin{aligned} \xi &= A \exp(i(kx - \omega t)) \\ \phi &= C \exp(i(kx - \omega t) + k_z z) \\ \phi' &= C' \exp(i(kx - \omega t) + k_z' z) \end{aligned}$$

↳ $\nabla^2 \phi = 0$ and $\phi \rightarrow 0$ as $z \rightarrow -\infty \Rightarrow k_z = k$

↳ similarly, $\nabla^2 \phi' = 0 \Rightarrow k_z = -k$

• At the interface, $u_z = \frac{D\xi}{Dt} \Rightarrow -\frac{\partial \Phi}{\partial z} = \frac{\partial \xi}{\partial t} + U \frac{\partial \xi}{\partial x}$

$$-\frac{\partial \Phi'}{\partial z} = \frac{\partial \xi}{\partial t} + U' \frac{\partial \xi}{\partial x}$$

↳ sub in plane wave solution $\therefore -kC = i(kU - \omega)A$

$$kC' = i(kU' - \omega)A$$

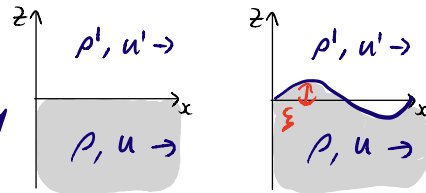
• Momentum equation $\Rightarrow \nabla \left[-\frac{\partial \Phi}{\partial t} + \frac{1}{2}u^2 + \frac{p}{\rho} + \Psi \right] = 0$

↳ must be $f(t)$

↳ pressure is continuous at the interface

$$\therefore \rho \left(-\frac{\partial \Phi}{\partial t} + \frac{1}{2}u^2 + g\xi \right) = \rho' \left(-\frac{\partial \Phi'}{\partial t} + \frac{1}{2}u'^2 + g\xi \right) + \rho f(t) - \rho' f'(t)$$

↳ $\rho f(t) - \rho' f'(t) \equiv K = \text{const}$ ← consider values at ∞



- Combine equations to get the dispersion relation:

$$\rho(kU - \omega)^2 + \rho'(kU' - \omega)^2 = kg(\rho - \rho')$$

- For surface gravity waves, the denser fluid is below
- ↳ $\rho' < \rho$ and let $U = U' = 0$ (fluids at rest)

↳ dispersion relation: $\omega^2 = k \frac{g(\rho - \rho')}{\rho + \rho'} \Rightarrow \frac{\omega}{k} = f(k)$

↳ if $\rho' \ll \rho$ (e.g. ocean), $\frac{\omega}{k} = \pm \sqrt{g/k}$

- If the denser fluid is on top (static):

$$\omega^2 = k \frac{g(\rho - \rho')}{\rho + \rho'} \Rightarrow \frac{\omega}{k} = \pm i \sqrt{\frac{g}{k} \frac{\rho' - \rho}{\rho + \rho'}}$$

↳ for $k \in \mathbb{R}$, ω is imaginary so there are exponentially growing/decaying solutions

↳ Rayleigh-Taylor instability

- If the denser fluid is below but fluids are moving:

↳ solve dispersion relation for $\frac{\omega}{k}$ ← quadratic

$$\Rightarrow \frac{\omega}{k} = \frac{\rho U + \rho' U'}{\rho + \rho'} \pm \sqrt{\frac{g}{k} \frac{\rho - \rho'}{\rho + \rho'} - \frac{\rho \rho' (U - U')^2}{(\rho + \rho')^2}}$$

↳ stability depends on sign inside square root

↳ if $g = 0$, always unstable → Kelvin-Helmholtz instability

↳ for $g \neq 0$, longer wavelengths are stabilised.

Thermal instability

- Consider perturbations of the energy equation

↳ first rewrite in terms of K

$$p = k\rho^\gamma = \frac{R^*}{M} \rho T$$

$$\Rightarrow dK = \rho^{1-\gamma} (1-\gamma) \left[\frac{p}{\rho^2} d\rho + \frac{R^*}{M(1-\gamma)} \alpha T \right]$$

$$= -\alpha Q$$

$$\Rightarrow \frac{DK}{Dt} = -(\gamma-1) \rho^{1-\gamma} \dot{Q}$$

↳ gives the **entropy form** of the energy equation

$$\frac{1}{K} \frac{DK}{Dt} = -(\gamma-1) \frac{\rho \dot{Q}}{p}$$

- Assume the fluid is a static ideal gas (no gravity) in thermal equilibrium: $u_0 = 0$, $\dot{Q}_0 = 0$, $\nabla K_0 = 0$

- Perturb and linearise:

$$\frac{\partial \Delta \rho}{\partial t} + \rho_0 \nabla \cdot (\Delta u) = 0$$

$$\rho_0 \frac{\partial \Delta u}{\partial t} = -\nabla (\Delta p)$$

$$\frac{\partial \Delta K}{\partial t} = -\frac{\gamma-1}{\rho_0^{\gamma-1}} \Delta \dot{Q} \leftarrow \text{sub } \Delta \dot{Q} = \frac{\partial \dot{Q}}{\partial p} \Big|_p \Delta p + \frac{\partial \dot{Q}}{\partial \rho} \Big|_p \Delta \rho$$

↳ seek plane wave solutions e.g. $\Delta \rho = \rho_1 e^{i\mathbf{k} \cdot \mathbf{x} + \eta t}$, such that $\text{Re}(\eta) > 0 \Rightarrow$ instability

↳ result is a cubic dispersion relation $E(\eta) = 0$

↳ unstable if the real root of $E(\eta)$ is > 0

↳ **Field criterion**: unstable if

$$\frac{\partial \dot{Q}}{\partial T} \Big|_p < 0$$

* ↳ i.e. unstable if cooling \downarrow as temp \uparrow

↳ e.g. power-law cooling of the form $\dot{Q} \propto T^\alpha$ is unstable for $\alpha < 1$ (Bremsstrahlung has $\alpha = 0.5$)

- If a system is field-unstable, all modes are unstable
- Even for field-stable systems, there may be unstable modes

↳ for large wavelengths (small K), $E(\eta) \approx \eta^2(\eta + A^* \rho_0^\gamma)$

↳ **isochoric thermal instability**: $\frac{\partial \dot{Q}}{\partial T} \Big|_p < 0$ \leftarrow density, not pressure

↳ for short wavelengths, sound waves bring pressure equilibrium so behaviour at const p matters

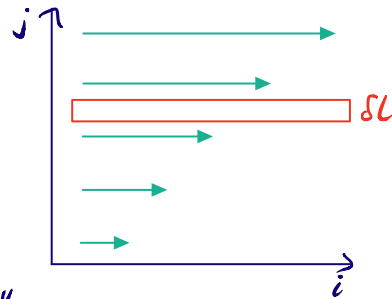
↳ for long wavelengths, there is insufficient time for pressure to equalise \rightarrow const ρ matters

- If gravity is included, buoyancy can stabilise thermal instabilities.

Viscous Flows

- We have assumed that changes in momentum are entirely due to pressure and gravity (valid for $\lambda \rightarrow 0$ limit) mean-free path
- For finite λ , momentum can diffuse through the fluid

- Consider a linear shear flow
 - ↳ in addition to bulk flow, there are random thermal velocities
 - ↳ Flux of i momentum in j direction



$$\langle p v_i v_j \rangle = \alpha \rho u_i \sqrt{\frac{k_B T}{m}}$$

bulk momentum density thermal velocity in j direction

- ↳ α is a constant of order 1. For hard spheres, $\alpha = \frac{\sqrt{3\pi}}{64}$
- ↳ the net momentum flux through a plane of thickness δL is: $-\rho (\partial_j u_i) \delta L \alpha \sqrt{\frac{k_B T}{m}}$
- ↳ $\delta L \approx \lambda = \frac{1}{n\sigma} = \frac{1}{n\sigma} = \frac{m}{\rho\sigma} = \frac{m}{\rho\pi a^2}$
- ⇒ momentum flux = $-(\partial_j u_i) \frac{m}{\sigma} \alpha \sqrt{\frac{k_B T}{m}}$

- This momentum flux modifies the momentum equation:

$$\frac{\partial}{\partial t} (\rho u_i) = -\partial_j (\rho u_i u_j + p \delta_{ij}) + \partial_j \left[\frac{\alpha}{\sigma} \sqrt{m k_B T} \partial_j u_i \right] + \rho g_i$$

- ↳ $\eta \equiv \frac{\alpha}{\sigma} \sqrt{m k_B T}$ is the shear viscosity

- ↳ η is independent of density \rightarrow more particles, but shorter λ
- ↳ $\eta \uparrow$ with T . Isothermal systems have $\eta = \text{const}$
- ↳ for Coulomb interactions, $\lambda \propto T^2 \Rightarrow \eta \propto T^{5/2}$

Navier-Stokes

- We can generalise to allow for viscous stresses in different directions

- Define the viscous stress tensor σ'_{ij} . It must be:

- Invariant to Galilean transformations
- Linear in velocity gradients
- Isotropic

- ↳ the most general tensor that satisfies this is

$$\sigma'_{ij} = \eta (\partial_j u_i + \partial_i u_j - \frac{2}{3} \delta_{ij} \partial_k u_k) + \zeta \delta_{ij} \partial_k u_k$$

shear flow bulk viscosity compression

- ↳ momentum equation: $\frac{\partial}{\partial t} (\rho u_i) = -\partial_j (\rho u_i u_j + p \delta_{ij} + \sigma'_{ij}) + \rho g_i$
- ↳ combining this with continuity gives the Navier-Stokes equation

- For an isothermal unshocked fluid, $\eta = \text{const}$ and $\zeta = 0$

$$\Rightarrow \frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} = -\frac{1}{\rho} \nabla p - \nabla \Phi + \frac{\eta}{\rho} [\nabla^2 \underline{u} + \frac{1}{3} \nabla (\nabla \cdot \underline{u})]$$

- ↳ $\frac{\eta}{\rho} \equiv \nu$ is the coefficient of kinematic viscosity

- The importance of viscosity is characterised by the Reynolds number

$$Re = \frac{|\underline{u} \cdot \nabla \underline{u}|}{|\nu \nabla^2 \underline{u}|} \sim \frac{U L}{\nu}$$

U is a velocity scale,
 L is a lengthscale

- ↳ viscosity important for small Re

- Viscosity allows for momentum transmission by shearing:

- ↳ stabilises fluid instabilities (i.e. damping)

- ↳ irreversibly dissipates KE as heat

- Vorticity: take the curl of the Navier-Stokes equation

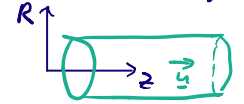
$$\Rightarrow \frac{\partial \underline{w}}{\partial t} = \nabla \times (\underline{u} \times \underline{w}) + \frac{\eta}{\rho} \nabla^2 \underline{w}$$

- ↳ viscosity allows for vorticity to diffuse through the fluid
- ↳ relative importance of advection/diffusion is given by Re
- ↳ vorticity can be introduced into an irrotational flow due to boundary interactions \rightarrow then diffuses into the bulk

I.4

Flow in a pipe

- Consider a steady-state, laminar, incompressible flow through a circular pipe (neglecting gravity)
- Neglect edge effects $\rightarrow u = u(R)$
- Navier-Stokes: $\frac{\partial u}{\partial t} + \underline{u} \cdot \nabla \underline{u} = -\frac{1}{\rho} \nabla p - \nabla \Phi + \nu (\nabla^2 \underline{u} + \frac{1}{3} \nabla (\nabla \cdot \underline{u}))$



$$\Rightarrow \nu \nabla^2 u = \frac{1}{\rho} \nabla p$$

$$\hookrightarrow \text{laminar} \Rightarrow u_R = u_\phi = 0 \Rightarrow \frac{\partial p}{\partial R} = \frac{\partial p}{\partial \phi} = 0$$

$$\hookrightarrow z\text{-component: } \nu \underbrace{\frac{1}{R} \frac{\partial}{\partial R} \left(R \frac{\partial u_z}{\partial R} \right)}_{R \text{ only}} = \underbrace{\frac{1}{\rho} \frac{\partial p}{\partial z}}_{z \text{ only}} = \text{const} = -\frac{1}{\rho} \frac{\Delta p}{L}$$

- Integrate equation to get $u = -\frac{\Delta p}{4\nu L} R^2 + a \ln R + b$

$$\hookrightarrow \text{finite at } R=0 \Rightarrow a=0 \Rightarrow u = \frac{\Delta p}{4\nu L} (R_0^2 - R^2)$$

$$\hookrightarrow u(R_0) = 0 \text{ (no slip)}$$

- Mass flux: $Q = \int_0^{R_0} 2\pi R \rho u \, dR$

- Beyond a certain Re (flow rate), there will be turbulence.

Accretion

- If infalling gas has net angular momentum (almost always true), Bondi accretion is not applicable. Gas tends to form **accretion disks** \rightarrow near-Keplerian orbits
- Accretion requires fluid elements to lose angular momentum
- Model a thin accretion disk in cylindrical coordinates:
 - \hookrightarrow axisymmetry $\Rightarrow \partial/\partial\phi = 0$
 - \hookrightarrow HSE vertically $\Rightarrow u_z = 0$
- Angular velocity: $\Omega = \sqrt{GM/R^3} \rightarrow$ varies with R so there will be shear between layers.
- Continuity: $\frac{\partial \rho}{\partial t} + \frac{1}{R} \frac{\partial}{\partial R} (\rho R u_R) + \frac{1}{R} \frac{\partial}{\partial \phi} (\rho u_\phi) + \frac{\partial}{\partial z} (\rho u_z) = 0$
 - $\Rightarrow \frac{\partial \rho}{\partial t} + \frac{1}{R} \frac{\partial}{\partial R} (R \rho u_R) = 0$
 - \hookrightarrow for accretion disks, the **surface density** is more relevant
 - $\Sigma \equiv \int_{-\infty}^{\infty} \rho dz \Rightarrow \frac{\partial \Sigma}{\partial t} + \frac{1}{R} \frac{\partial}{\partial R} (R \Sigma u_R) = 0$
 - \hookrightarrow can also derive directly by considering flow of mass in/out of annulus
- Likewise for the momentum equation, we can use Navier-Stokes or consider annuli:
 - $\hookrightarrow \frac{d}{dt} (\text{angular momentum}) = \text{ang mtr in} - \text{ang mtr out} + \text{net torque}$
 - $\Rightarrow \frac{\partial}{\partial t} (2\pi R \Delta R \Sigma \Omega R^2) = f(R) - f(R+\Delta R) + G(R+\Delta R) - G(R)$
 - $\hookrightarrow f(R) \equiv 2\pi R \Sigma u_R \Omega R^2$ describes the advection of ang mtr

$$\hookrightarrow \text{viscous torque: } G(R) = 2\pi R \nu \Sigma R \frac{\partial \Omega}{\partial R} R = 2\pi R^3 \nu \Sigma \frac{d\Omega}{dR}$$

$$\Rightarrow \frac{\partial}{\partial t} (R \Sigma u_\phi) = -\frac{1}{R} \frac{\partial}{\partial R} (\Sigma R^2 u_\phi u_R) + \frac{1}{R} \frac{\partial}{\partial R} (\nu \Sigma R^3 \frac{d\Omega}{dR})$$

For an axisymmetric orbit, $\frac{\partial u_\phi}{\partial t} = 0$

$$\Rightarrow u_R = \frac{\frac{\partial}{\partial R} (\nu \Sigma R^3 \frac{d\Omega}{dR})}{R \Sigma \frac{\partial}{\partial R} (R^2 \Omega)}$$

\hookrightarrow sub u_R into continuity eq and use Newtonian point source

$$\text{with } \Omega = \sqrt{GM/R^3} \Rightarrow \frac{\partial \Sigma}{\partial t} = \frac{3}{R} \frac{\partial}{\partial R} \left[R^{1/2} \frac{\partial}{\partial R} (\nu \Sigma R^{1/2}) \right]$$

\hookrightarrow surface density obeys a diffusion-like equation

\hookrightarrow if $\nu = \nu(R)$ only, it becomes a linear diffusion equation

\hookrightarrow hence narrow rings start to spread out, becoming disks.

Estimate accretion time:

$$\frac{\Sigma}{t_v} \sim \frac{1}{R} \cdot \frac{1}{R} \left[R^{1/2} \frac{1}{R} \nu \Sigma R^{1/2} \right] \sim \frac{\nu \Sigma}{R^2}$$

$$\Rightarrow t_v \sim \frac{R^2}{\nu} = \frac{R}{u_\phi} \frac{R u_\phi}{\nu} = \Omega^{-1} \cdot Re$$

\hookrightarrow kinetic theory gives very small $\nu \rightarrow$ accretion timescale greater than the age of the universe

\hookrightarrow i.e. the 'viscosity' driving accretion cannot be microphysical viscosity \rightarrow believed to be due to turbulence.

$\hookrightarrow [v] = [L]^2 [T]^{-1} = [u][L]$. Using the characteristic quantities in a disk, $\nu = \alpha c_s H$, where $\alpha < 1 = \text{const}$

Steady-state accretion disks

- Energy dissipation per unit area of disk

$$\begin{aligned} \text{Flux} \rightarrow F_{\text{disk}} &= - \int \sigma_{ij} \partial_j u_i u_i \frac{dV}{2\pi R dR dz} \\ &= \frac{1}{2} \int \eta (\partial_j u_i + \partial_i u_j)^2 dz \\ &= \int \eta R^2 \left(\frac{d\Omega}{dR} \right)^2 dR = \nu \Sigma R^2 \left(\frac{d\Omega}{dR} \right)^2 \end{aligned}$$

- Continuity: $\frac{\partial \Sigma}{\partial t} + \frac{1}{R} \frac{\partial}{\partial R} (R \Sigma U_r) = 0$

$$\rightarrow \text{steady state} \Rightarrow R \Sigma U_r = C_1 = -\frac{\dot{m}}{2\pi} \leftarrow \dot{m} \text{ positive for inflow}$$

$$\Rightarrow U_r = -\frac{\dot{m}}{2\pi R \Sigma}$$

- Axisymmetric orbit: $U_r = \frac{\partial}{\partial R} \left(\frac{\nu \Sigma R^3 \frac{d\Omega}{dR}}{R \Sigma \frac{\partial}{\partial R} (R^2 \Omega)} \right)$

\rightarrow steady state accretion around a point mass ($R^2 = \frac{GM}{\Omega^2}$)

$$\Rightarrow -\frac{\dot{m}}{2\pi R \Sigma} = -\frac{3}{\Sigma R^{1/2}} \frac{\partial}{\partial R} (\nu \Sigma R^{1/2})$$

\rightarrow integrate with inner torque boundary condition \rightarrow no viscous

torque at some inner radius i.e. $\nu \Sigma = 0$ at $R = R_*$

$$\Rightarrow \nu \Sigma = \frac{\dot{m}}{3\pi} \left(1 - \sqrt{\frac{R_*}{R}} \right)$$

- Sub into dissipation formula: $F_{\text{disk}} = \frac{36M\dot{m}}{4\pi R^3} \left(1 - \sqrt{\frac{R_*}{R}} \right)$

$$\rightarrow \text{total energy emitted: } L = \int_{R_*}^{\infty} F_{\text{disk}} \cdot 2\pi R dR = \frac{GM\dot{m}}{2R_*}$$

\rightarrow i.e. disk radiates half of the accreting matter's binding energy

\rightarrow other half is KE of infalling matter

- Far from the inner disk, $F_{\text{disk}} \approx \frac{36M\dot{m}}{4\pi R^3}$

\rightarrow the local rate of loss of binding energy is:

$$F_{\text{disk,est}} = \underbrace{\frac{1}{2\pi R dR}}_{\text{area of annulus}} \cdot \underbrace{\left| \frac{\partial}{\partial R} \left(\frac{GM\dot{m}}{R} \right) \right|}_{\Delta \text{GPE}} \cdot \underbrace{\frac{1}{2}}_{1/2 \text{ radiated}} = \frac{6M\dot{m}}{4\pi R^3}$$

\rightarrow i.e. $2/3$ of dissipated energy is not from ΔGPE

\rightarrow source is viscous transport of energy from inner \rightarrow outer disk

- Can estimate disk temp assuming BB radiation:

$$\rightarrow \begin{matrix} \text{top} \\ \text{bottom} \end{matrix} \Rightarrow 2 \cdot \sigma T_{\text{eff}}^4 = \frac{36M\dot{m}}{4\pi R^3} \left(1 - \sqrt{\frac{R_*}{R}} \right)$$

\rightarrow at large distances, $T_{\text{eff}} \propto R^{-3/4}$

- All observables are independent of viscosity \rightarrow need to observe non-steady disks to learn about ν .

Plasmas

Magnetohydrodynamics (MHD)

- Model fully ionized hydrogen as two cohabiting fluids:

1. Proton fluid $m^+, n^+, \underline{u}^+$

2. Electron fluid $m^-, n^-, \underline{u}^-$

- Aggregate properties of fluid:

↳ density $\rho = m^+ n^+ + m^- n^-$

↳ COM velocity is the density-weighted avg: $\underline{u} = \frac{m^+ n^+ \underline{u}^+ + m^- n^- \underline{u}^-}{\rho}$

↳ charge density $q = n^+ e^+ + n^- e^-$

↳ current density $\underline{j} = e^+ n^+ \underline{u}^+ + e^- n^- \underline{u}^-$

- Conserve particle number: $\frac{\partial n^\pm}{\partial t} + \nabla \cdot (n^\pm \underline{u}^\pm) = 0$

↳ multiply eqns by m^\pm to get $\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \underline{u}) = 0$ ← standard continuity

↳ multiply by e^\pm to get charge conservation: $\frac{\partial q}{\partial t} + \nabla \cdot \underline{j} = 0$

- Momentum equation:

↳ Lorentz force on each particle: $\underline{F} = q(\underline{E} + \underline{u} \times \underline{B})$

↳ for each fluid: $\frac{\partial (m^\pm n^\pm \underline{u}^\pm)}{\partial t} + \nabla \cdot (m^\pm n^\pm \underline{u}^\pm \underline{u}^\pm) = e^\pm n^\pm (\underline{E} + \underline{u}^\pm \times \underline{B}) - f^\pm \nabla p$
fraction of pressure gradient attributed to each fluid

$$m^\pm n^\pm \left(\frac{\partial \underline{u}^\pm}{\partial t} + \underline{u}^\pm \cdot \nabla \underline{u}^\pm \right) = e^\pm n^\pm (\underline{E} + \underline{u}^\pm \times \underline{B}) - f^\pm \nabla p$$

↳ sum: $\rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = -\nabla p + q \underline{E} + \underline{j} \times \underline{B}$ new terms

- Ohm's law connects \underline{j} with the electromagnetic fields:

$\underline{j} = \sigma (\underline{E} + \underline{u} \times \underline{B})$ where σ is the conductivity.

- Equations of MHD:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \underline{u}) = 0$$

Mass continuity

$$\frac{\partial q}{\partial t} + \nabla \cdot \underline{j} = 0$$

Charge continuity

$$\rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = -\nabla p + q \underline{E} + \underline{j} \times \underline{B}$$

Momentum

$$\underline{j} = \sigma (\underline{E} + \underline{u} \times \underline{B})$$

Ohm's law

+ Maxwell's equations

Ideal MHD

- Consider a non relativistic and highly conducting plasma
- Approx fields as varying over lengthscale l and timescale τ .

$$\nabla \times \underline{E} = -\frac{\partial \underline{B}}{\partial t} \Rightarrow \frac{E}{l} \sim \frac{B}{\tau} \Rightarrow \frac{E}{B} \sim u$$

$$\left| \frac{\frac{1}{c^2} \frac{\partial \underline{E}}{\partial t}}{|\nabla \times \underline{B}|} \right| \sim \frac{1}{c^2} \left(\frac{l}{\tau} \right)^2 \sim \frac{u^2}{c^2} \ll 1 \quad (\text{non-relativistic})$$

↳ can ignore displacement current $\Rightarrow \nabla \times \underline{B} = \mu_0 \underline{j}$

$$\frac{|q \underline{E}|}{|\underline{j} \times \underline{B}|} \sim \frac{q E}{j B} \sim \frac{\epsilon_0 (\nabla \cdot \underline{E}) E}{\frac{1}{\mu_0} |\nabla \times \underline{B}| B} \sim \frac{\epsilon_0 E / L E}{\frac{1}{\mu_0} B / L B} \sim \frac{u^2}{c^2} \ll 1$$

↳ $q \underline{E}$ is negligible in the momentum eq.

↳ i.e charge neutrality is preserved

- Combine Ampere/Ohm: $\nabla \times \underline{B} = \mu_0 \underline{j} = \mu_0 \sigma (\underline{E} + \underline{u} \times \underline{B})$

↳ take curl $\Rightarrow \frac{\partial \underline{B}}{\partial t} = \nabla \times (\underline{u} \times \underline{B}) + \frac{1}{\mu_0 \sigma} \nabla^2 \underline{B}$ ← same form as vorticity

↳ good conductor $\Rightarrow \sigma$ large $\Rightarrow \frac{\partial \underline{B}}{\partial t} = \nabla \times (\underline{u} \times \underline{B})$

- ↳ magnetic flux is 'frozen' into the plasma
- For a good conductor, $\underline{E} + \underline{u} \times \underline{B} = \frac{1}{\sigma} \underline{j} \rightarrow 0 \Rightarrow \underline{E} \perp \underline{B}$
- Ideal momentum equation: $\rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = -\nabla p + \frac{1}{\mu_0} (\nabla \times \underline{B}) \times \underline{B}$


- ↳ electromagnetic force per unit volume is $\underline{f}_{mag} = \frac{1}{\mu_0} (\nabla \times \underline{B}) \times \underline{B}$
- ↳ using vector identity: $\underline{f}_{mag} = \frac{1}{\mu_0} \left[-\nabla \left(\frac{B^2}{2} \right) + (\underline{B} \cdot \nabla) \underline{B} \right]$
magnetic pressure magnetic tension
- ↳ can absorb magnetic pressure into ∇p to get:
 $\rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = \frac{1}{\mu_0} (\underline{B} \cdot \nabla) \underline{B} - \nabla p_{tot} \leftarrow p_{tot} = p + \frac{B^2}{2\mu_0}$

MHD waves

- New terms in the momentum eq \rightarrow different waves.
- Perturb density, pressure, fluid velocity, B-field \leftarrow assume barotropic EOS
- Seek plane wave solutions, e.g. $\Delta \underline{B} = \Delta \underline{B}_0 e^{i(\underline{k} \cdot \underline{r} - \omega t)}$
- ↳ $\frac{\partial}{\partial t} \rightarrow -i\omega$, $\nabla \rightarrow i\underline{k}$
- ↳ continuity $\rightarrow \omega \Delta \rho = \rho_0 \underline{k} \cdot \Delta \underline{u}$
- ↳ momentum $\rightarrow \omega \rho_0 \Delta \underline{u} = \frac{1}{\mu_0} [(\underline{B}_0 \cdot \nabla) \Delta \underline{B} - (\underline{B}_0 \cdot \underline{k}) \Delta \underline{B}] + G^2 \Delta \rho \underline{k}$
- ↳ flux-freezing $\rightarrow \omega \Delta \underline{B} = \underline{B}_0 (\underline{k} \cdot \Delta \underline{u}) - (\underline{B}_0 \cdot \underline{k}) \Delta \underline{u}$


- ① Perturbation perpendicular to field, $\underline{k} \perp \underline{B}_0$
- ↳ simplify eqns then eliminate $\Delta \rho, \Delta \underline{B}$
- ↳ $\Delta \underline{u} \propto \underline{k}$ so this is a longitudinal mode
- ↳ result is $\omega^2 = \left(c_s^2 + \frac{B^2}{\mu_0 \rho_0} \right) k^2$

- ↳ define the Alfvén speed $v_A = \sqrt{\frac{B^2}{\rho \mu_0}} \Rightarrow \omega^2 = (c_s^2 + v_A^2) k^2$
- ↳ it is a fast magnetosonic wave, travelling faster than the sound speed due to magnetic pressure.

- ② Perturbation parallel to field, $\underline{k} \parallel \underline{B}_0$
- ↳ $\omega^2 = \frac{B_0^2}{\mu_0 \rho_0} k^2 \Rightarrow \omega^2 = v_A^2 k^2 \leftarrow$ Alfvén waves
- ↳ transverse incompressible waves due to magnetic tension 
- ↳ another permitted solution is the standard sound wave

- For a general perturbation ($\underline{B}, \underline{k}$ at angle θ) there are 3 modes: Alfvén wave, fast magnetosonic, slow magnetosonic

Magneto-rotational instability

- Consider the local frame of a patch in an accretion disk 
- Momentum eq:
 $\frac{D\underline{u}}{Dt} = \underbrace{-\frac{1}{\rho} \nabla p}_{\text{pressure gradient}} + \underbrace{\frac{1}{\mu_0 \rho} (\nabla \times \underline{B}) \times \underline{B}}_{\text{magnetic force}} + \underbrace{2\underline{u} \times \underline{\Omega}}_{\text{Coriolis}} + \underbrace{\underline{\Omega} \times (\underline{\Omega} \times \underline{r})}_{\text{centrifugal}} - \underbrace{\frac{R \cdot \Omega_k (R)^2}{\rho}}_{\text{gravity}} \hat{R}$
- Assume:
 - ↳ uniform field $\underline{B}_0 = B_0 \hat{z} \leftarrow$ aligned with $\underline{\Omega}$
 - ↳ cold gas \rightarrow ignore pressure
 - ↳ only consider $\underline{k} \parallel \underline{B}_0$ perturbations

• Perturbed eqn: $\frac{D\Delta\mathbf{u}}{Dt} - 2\Delta\mathbf{u} \times \underline{\Omega} = \frac{1}{\rho_0} (\underline{B}_0 \cdot \nabla) \Delta\mathbf{B} - \underbrace{\Delta x R \frac{d\Omega^2}{dR}}_{\text{mismatch of centri/gravity}}$

↳ seek plane wave solutions and use MHD eqs to get expression for $\Delta\mathbf{B}$

↳ result: $\omega^4 - \omega^2 \left[4\Omega^2 - \frac{d\Omega^2}{d \ln R} + 2(KV_A)^2 \right] + (KV_A)^2 \left[(KV_A)^2 + \frac{d\Omega^2}{d \ln R} \right] = 0$

• Ignoring magnetic physics: $\omega^2 = 4\Omega^2 + \frac{d\Omega^2}{d \ln R} = \frac{1}{R^3} \frac{d}{dR} (R^4 \Omega^2) \equiv \kappa_R^2$

↳ if $\kappa_R^2 > 0$ we get radial epicyclic approximations

↳ if $\kappa_R^2 < 0$ (i.e. h decreases with radius), the flow is unstable.

• Including magnetism, unstable if $\omega^2 < 0 \Rightarrow (KV_A)^2 + \frac{d\Omega^2}{d \ln R} < 0$

↳ if the field is weak, KV_A is negligible

\Rightarrow unstable if $\frac{d\Omega^2}{d \ln R} < 0$

↳ hence even Keplerian flow is unstable \rightarrow magnetorotational instability.

↳ MRI is stabilised if $K > K_{\text{crit}}$:

$(K_{\text{crit}} VA)^2 = -\frac{d\Omega^2}{d \ln R} = 3\Omega^2$ in Keplerian case